



## Polbox – Longterm SoP Acquisition

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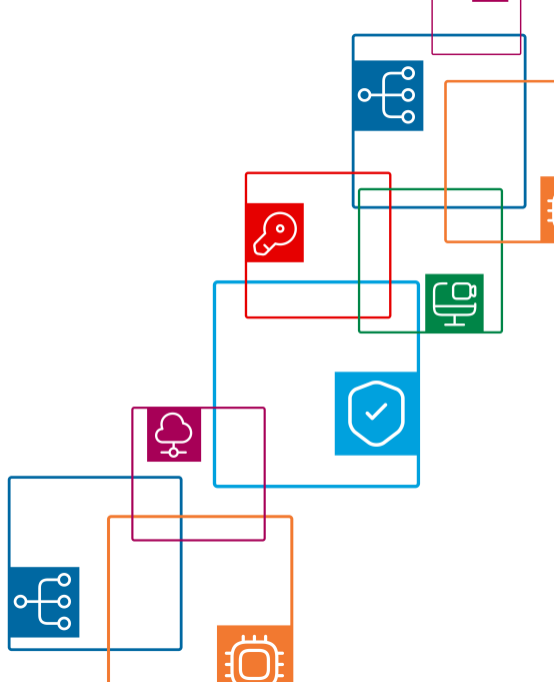




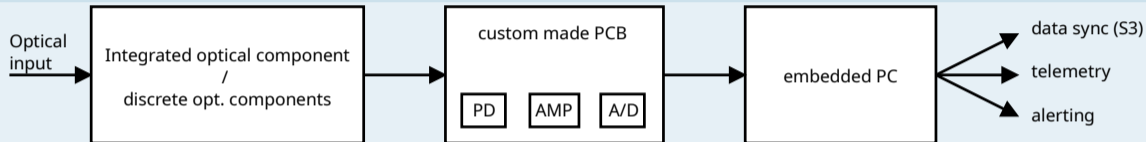
Figure 1: The Polbox prototype developed for SUBMERSE project



- ▶ Long-term continuous SoP acquisition.
- ▶ Fast sampling rate at 20 kHz, 4 channels with 16 bit resolution per channel.
- ▶ Variable optical input source: a tap on **existing signal**, or custom laser source.
  - ▶ Prototypes are capable to operate from 1270 to 1610 nm (ideal 1520–1610 nm).
  - ▶ Optical input power from -15 to 15 dBm (special version from -35 to 5 dBm).
- ▶ Durable 1U 19" chassis with dual power sources.
- ▶ Monitoring compatible with Influx DB and Grafana.
- ▶ Local embedded SSD storage, optionally synchronized to the remote filesystem or object storage (S3 compatible).



## Block schema of Polbox



- ▶ State of Polarization – orientation and trajectory of the vector of the electric field.
- ▶ Two principal states – horizontal and vertical (and anything in between).
  - ▶ Linear, circular, elliptical polarizations.
- ▶ No reason to go into the theory – but all of us know Polarization Sunglasses, right?
- ▶ Only one polarization can pass through.



- ▶ Detecting acoustic-mechanical vibrations and disturbances in fibre and its neighbourhood – e.g. for seismic activity.
- ▶ Physical perimeter intrusion detection.
- ▶ Critical infrastructure manipulation alerting system.
- ▶ Long-term SoP acquisition for later analysis or on-the-flow processing.



# Use-cases II

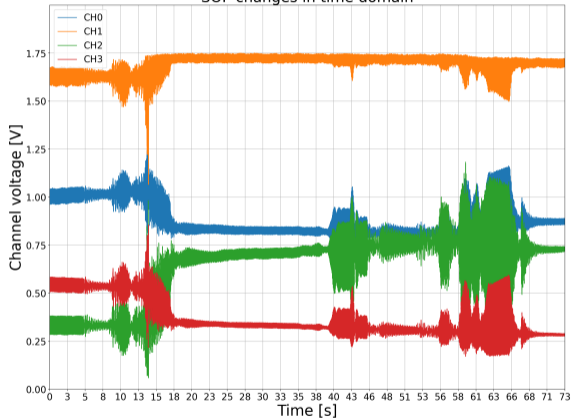
Practical notes and technology limitations

- ▶ Important to mention one big difference between SoP and DAS equipment.
- ▶ **SoP cannot tell us where the disturbance is.**
- ▶ This can be pretty important for some use-cases, or users.
  - ▶ It is possible, using one well-know Speed-Distance-Time (SDT) equation.
  - ▶ distance = speed x time, easy, huh? Like vehicles accidents. . .
  - ▶ But photons are pretty quick vehicles, travelling 200 000 km/s.
  - ▶ This equals 0.2 m in 1 nanosecond. 200 m in 1 microsecond. And 200 km in 1 millisecond.
- ▶ What does this mean?
- ▶ We need very accurate time stamping methods like *White Rabbit*.
  - ▶ Sampling every 1 ms (1 kHz) is really not good enough.
  - ▶ This sampling rate is used in coherent transceivers. They can report SoP but spatial resolution is as written above.

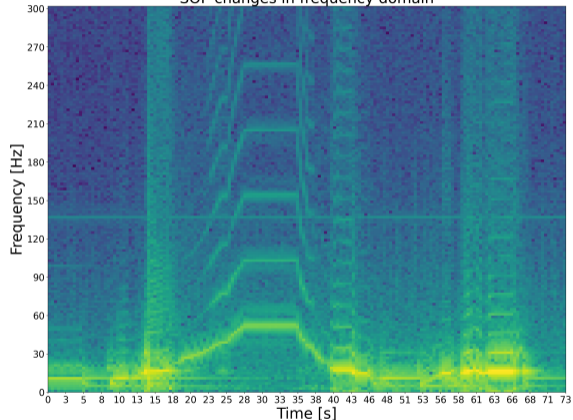


# Example data

SOP changes in time domain



SOP changes in frequency domain



### Raw data stream

```
#          S0/raw0  S1/raw1  S2/raw2  S3/raw3
array ([[ 0.1234,  0.2345,  0.3456,  0.4567], # row 0
         [ 0.2234,  0.3345,  0.4456,  0.5567], # row 1
         [ 0.3234,  0.4345,  0.5456,  0.6567], # row 2
         ...
         [ 0.8765,  0.1111,  0.2222,  0.3333]]) # row N
```

- ▶ In case of uncalibrated unit, there are 4 raw values of photodiode's voltage instead of S0–S3.



- ▶ Recorded SoP *raw time-series data* are stored locally in HDF5 format with *metadata* describing the recording context, acquisition parameters and could be synchronized to the remote storage.
- ▶ The format is designed to be compact, self-descriptive, and easily readable from common scientific tools such as Python (h5py, pandas) or MATLAB.
- ▶ **Actually, there is no standard for SoP data storage format and we have proposed the initial draft and working hard on the first public version.**
- ▶ Depending on the input signal, the recorded data stream approximately needs 6-13 GB daily (DAS data volume starts at 1 TB/day).
- ▶ Actual data file is rotated each hour (configurable).



## Metadata format

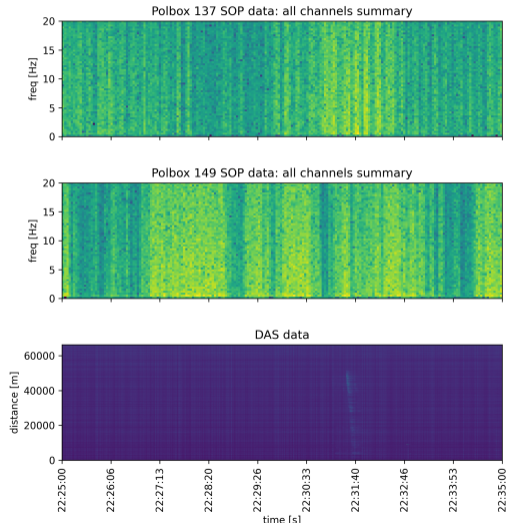
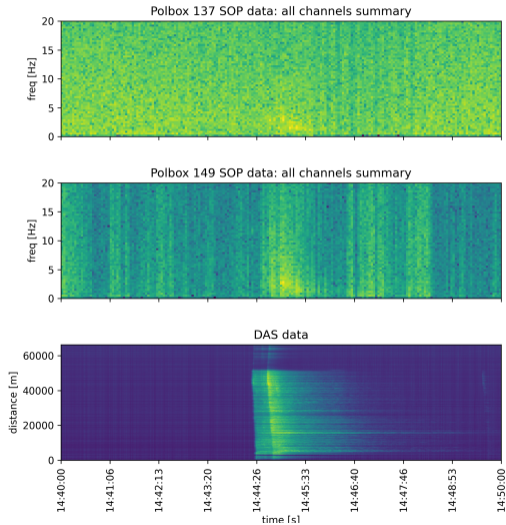
<code>creator: str</code>	Identifier of the software that created the dataset.
<code>description: str</code>	Experiment description.
<code>channels: int</code>	Number of channels   typically 4.
<code>sampling_frequency: int</code>	Sampling frequency in Hz (default: 20000).
<code>timezone: str</code>	Time zone offset in the format +XX:YY.
<code>timezone_name: str</code>	Time zone name (e.g., CEST).
<code>channel_unit: str</code>	Unit of the channel data, typically Volt or a normalized unit.
<code>samples: int</code>	Number of samples per channel.
<code>duration: float</code>	Duration of the recording in seconds.
<code>epoch_start: unix_timestamp</code>	Unix timestamp of the recording start.
<code>epoch_written: unix_timestamp</code>	Unix timestamp of when the dataset was written to disk.
<code>timestamp_start: str</code>	Human-readable timestamp of the recording start.
<code>timestamp_written: str</code>	Human-readable timestamp of when the dataset was written to disk.
<code>events: str</code>	JSON object containing event annotations (see the documentation for details).

- ▶ Two types of an event annotation: *interval* – covers a defined time span, or *event* – represents a single point in time.

### Metadata for event annotation

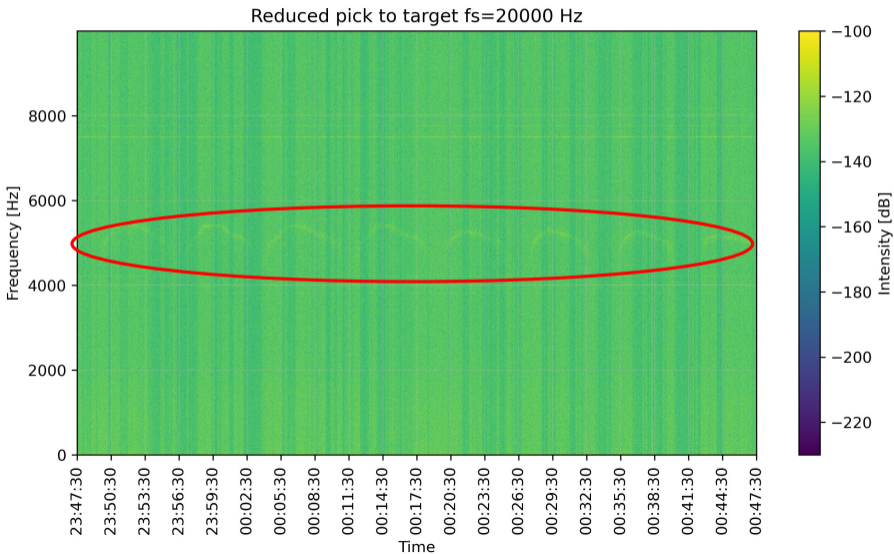
<code>start: int</code>	Index (sample number) of the event start.
<code>end: int   null</code>	Index (sample number) of the event end; null for point event.
<code>time_start: str</code>	Human-readable timestamp of the event start.
<code>time_end: str   null</code>	Human-readable timestamp of the event end; null for point event.
<code>label: str</code>	A human-readable label.
<code>label_class: str</code>	Event class, or an empty string "" if not classified.
<code>annotation_type: str</code>	Type of annotation: "event"   "interval".
<code>detector: str</code>	Description or identifier of the detector or detection method.
<code>score: float</code>	Event score (e.g., class probability or confidence value).
<code>properties: dict</code>	Additional properties of the event.
-> <code>freq_low: float</code>	Lower frequency of the event.
-> <code>freq_up: float</code>	Upper frequency of the event.
-> <code>channel: int</code>	Channel number (0-3).

# Example data – SUBMERSE SoP and DAS aligned



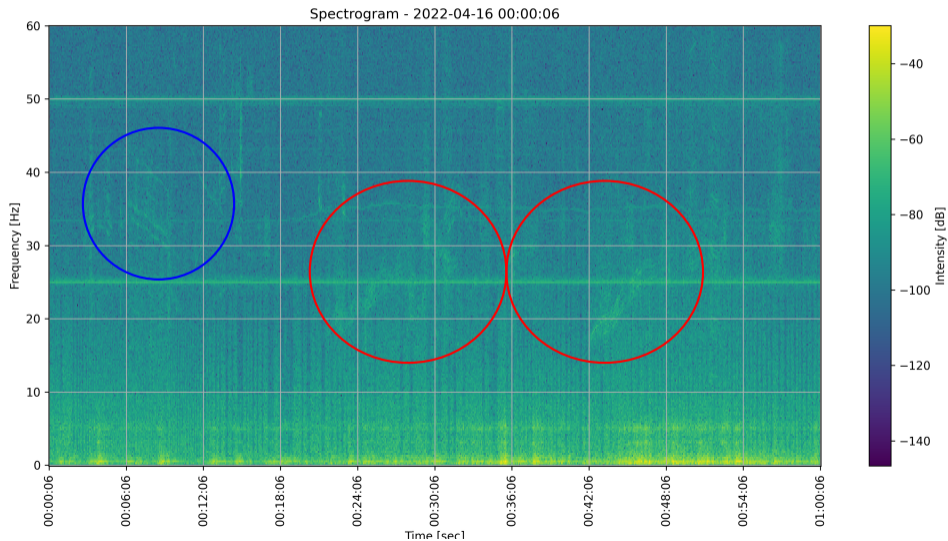
# Example data – SUBMERSE SoP

A periodic signal at 5.5 kHz



# Example data – terrestrial SoP

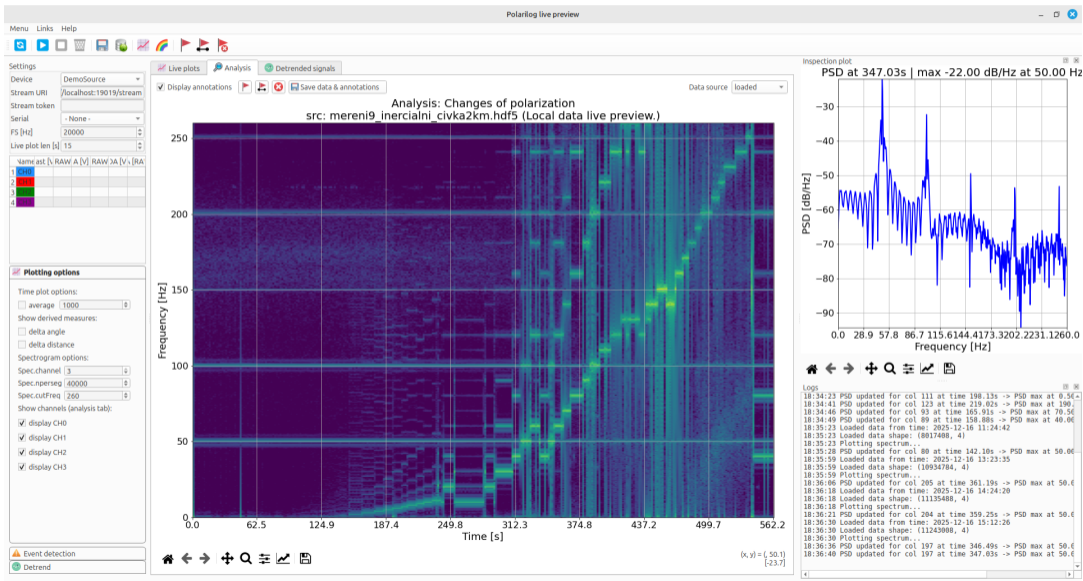
Disturbances along the railway



- ▶ A specific SoP data analysis is made in Python, utilizing well known tools as *h5py*, *scipy*, *matplotlib*, *pandas*, ... with focus on particular task.
- ▶ Common routines as data plotting in time/frequency domain were already prepared as parametrized scripts.
- ▶ For live demonstration we have developed a GUI (Polive) capable of recording, displaying the live time and frequency domain graphs, support for manual event annotation and also offline analysis and annotation.
- ▶ We have been working on the automated event detection with several approaches both in time and frequency domains.
- ▶ **The problem is unlabeled data: We see something but cannot say what it is!**

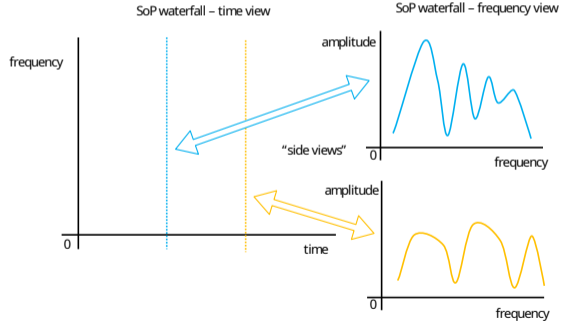
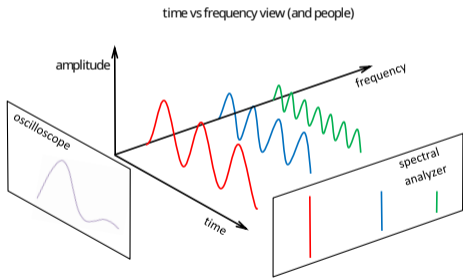


# Analysis tools – Polive GUI








# Frequency vs. Time Views

- ▶ It seems there are two groups of scientific/research people.
- ▶ One group see in the time domain and the other group in the frequency domain.
- ▶ You?:-)



- ▶ SoP is one alternative to DAS (Interferometric methods also available.).
  - ▶ Producing significantly less data.
  - ▶ Can detect higher frequencies easily.
  - ▶ Localization of events not easy but possible (more details in the first reference – OFC2025).
- ▶ CESNET Polbox – transfer of know-how to the license partners.
- ▶ Thanks to colleagues from CESNET.
- ▶ Thank you for your kind attention.



-  N. Okada et al., *Demonstration of State-of-Polarization Change Localization Based on Digital Coherent Transceivers*, OFC 2025, paper M3Z.1.
-  GN5-2-White-Paper\_Fibre-Sensing Technologies.pdf
-  GN5-2-WP6-White-Paper\_Fibre Sensing: Technologies, Users and Use Cases for NRENs
-  Tapping into the ground: terrestrial applications of Distributed Fibre Sensing
-  GÉANT Infoshare: Backscattering based sensing technologies, equipment and use cases

